

Optimal Parenting Styles: Evidence from a Dynamic Game with Multiple Equilibria

Marco Cosconati

Bank of Italy & IZA

FINET Workshop November 2012

Introduction

Motivation

- The impact of parental home inputs on children's outcomes has been widely studied by economists

Introduction

Motivation

- The impact of parental home inputs on children's outcomes has been widely studied by economists
- The effectiveness of alternative parenting strategies in producing desirable child outcomes has been investigated by researchers in child development and sociology

Introduction

Motivation

- The impact of parental home inputs on children's outcomes has been widely studied by economists
- The effectiveness of alternative parenting strategies in producing desirable child outcomes has been investigated by researchers in child development and sociology
- It is controversial if leaving discretion to children is a better approach to parenting than setting strict limits

Introduction

Motivation

- The impact of parental home inputs on children's outcomes has been widely studied by economists
- The effectiveness of alternative parenting strategies in producing desirable child outcomes has been investigated by researchers in child development and sociology
- It is controversial if leaving discretion to children is a better approach to parenting than setting strict limits
- It has been recently suggested that the “Tiger” parenting model, as opposed to “Western” parenting, is the main source of academic success of Asian children with respect to their peers
- Addressing this debate has potentially important implications for public policies that ease parents' monitoring cost by restricting children's recreational activities

Introduction

Parenting in Economics

- The strategic interaction between parents and children has received limited attention in economics
 - Most of the existing models of interaction between parents and children are static (Lizzeri&Siniscalchi (QJE 2008), Akabayshi (JEDC 1995), Weinberg (JPE 2001), Hotz, Hao and Jin (EJ 2008))

Introduction

Parenting in Economics

- The strategic interaction between parents and children has received limited attention in economics
 - Most of the existing models of interaction between parents and children are static (Lizzeri&Siniscalchi (QJE 2008), Akabayshi (JEDC 1995), Weinberg (JPE 2001), Hotz, Hao and Jin (EJ 2008))
- The purpose of this paper is to address the "parenting-debate" by analyzing the development of adolescent skills as an equilibrium outcome of the *repeated* interaction between parents and children

Introduction

Parenting in Economics

- The strategic interaction between parents and children has received limited attention in economics
 - Most of the existing models of interaction between parents and children are static (Lizzeri&Siniscalchi (QJE 2008), Akabayshi (JEDC 1995), Weinberg (JPE 2001), Hotz, Hao and Jin (EJ 2008))
- The purpose of this paper is to address the "parenting-debate" by analyzing the development of adolescent skills as an equilibrium outcome of the *repeated* interaction between parents and children
- I extended my previous work by estimating a "fully" dynamic model whose equilibria hold under standard conditions adopted in the principal-agent model literature and abstracting from *permanent* asymmetric information
- Results indicate that the dynamic aspect is important to understand the quantitative impact of alternative parenting strategies

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Each questions has three mutually exclusive possible answers:

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Each questions has three mutually exclusive possible answers:

- PARENT OR PARENTS SET LIMITS

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Each questions has three mutually exclusive possible answers:

- PARENT OR PARENTS SET LIMITS
- PARENTS LET ME DECIDE

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Each questions has three mutually exclusive possible answers:

- PARENT OR PARENTS SET LIMITS
- PARENTS LET ME DECIDE
- MY PARENTS AND I DECIDE JOINTLY

Introduction

Parenting in the Data

- Data from the NLSY97 indicate that parental choices regarding limits vary across households

The *Autonomy/Parental control* section contained in the NLSY97 *Youth Questionnaire* asks, among others, the following questions: “Who sets the limits on...

- : how late you stay out at night?”
- : who you can hang out with?”
- : what kinds of tv shows and movies you watch?”

Each questions has three mutually exclusive possible answers:

- PARENT OR PARENTS SET LIMITS
- PARENTS LET ME DECIDE
- MY PARENTS AND I DECIDE JOINTLY

Introduction

Statistics on Parenting Styles

Table: Curfew Limit by Age

	12-13	13-14	14-15
Parents	67.04	54.79	46.31
Jointly/Child	32.96	45.21	53.69
N	1341	1305	1274

1984 cohort

Introduction

Statistics on Parenting Styles

Table: Curfew Limit by Age

	12-13	13-14	14-15
Parents	67.04	54.79	46.31
Jointly/Child	32.96	45.21	53.69
N	1341	1305	1274

1984 cohort

Table: Friends Limit by Age

	12-13	13-14	14-15
Parents	22.09	11.67	9.08
Jointly/Child	77.91	88.33	90.92
N	1340	1302	1278

1984 cohort

Introduction

Statistics on Parenting Styles

Table: Curfew Limit by Age

	12-13	13-14	14-15
Parents	67.04	54.79	46.31
Jointly/Child	32.96	45.21	53.69
N	1341	1305	1274

1984 cohort

Table: Friends Limit by Age

	12-13	13-14	14-15
Parents	22.09	11.67	9.08
Jointly/Child	77.91	88.33	90.92
N	1340	1302	1278

1984 cohort

Table: TV Limit by Age

	12-13	13-14	14-15
Parents	35.94	19.23	14.01
Jointly/Child	64.06	80.77	85.99
N	1341	1305	1278

1984 cohort

Introduction

Statistics on Parental Limits

Table: Curfew by Race

	Black	Hispanic	White
Parents	75.76	67.45	64.82
Jointly/Child	24.24	32.55	35.18
N	435	381	901

1984 cohort, age:12-13

Introduction

Statistics on Parental Limits

Table: Curfew by Race

	Black	Hispanic	White
Parents	75.76	67.45	64.82
Jointly/Child	24.24	32.55	35.18
N	435	381	901

1984 cohort, age:12-13

Table: Friends Limit by Race

	Black	Hispanic	White
Parents	34.59	28.16	17.44
Jointly/Child	65.41	71.84	82.56
N	425	380	900

1984 cohort, age:12-13

Introduction

Statistics on Parental Limits

Table: Curfew by Race

	Black	Hispanic	White
Parents	75.76	67.45	64.82
Jointly/Child	24.24	32.55	35.18
N	435	381	901

1984 cohort, age:12-13

Table: Friends Limit by Race

	Black	Hispanic	White
Parents	34.59	28.16	17.44
Jointly/Child	65.41	71.84	82.56
N	425	380	900

1984 cohort, age:12-13

Table: TV Limit by Race

	Black	Hispanic	White
Parents	35.53	35.96	37.36
Jointly/Child	67.47	64.04	62.64
N	435	381	902

1984 cohort, age:12-13

Introduction

Statistics on Parental Limits

Table: Average PIAT and Limits

	Limits on TV	Limits on Curfew	Limits on Friends
Jointly/Child	73.66	75.66	74.48
Parents	70.49	70.87	66
T-test	0.02	0	0

all cohorts, pooled data

Introduction

Statistics on Parental Limits

Table: Average PIAT and Limits

	Limits on TV	Limits on Curfew	Limits on Friends
Jointly/Child	73.66	75.66	74.48
Parents	70.49	70.87	66
T-test	0.02	0	0

all cohorts, pooled data

Table: Average GPA and Limits

	Limits on TV	Limits on Curfew	Limits on Friends
Jointly/Child	280.1	287.79	282.23
Parents	293.6	271.38	271.14
T-test	0.35	0.04	0.42

all cohorts, pooled data

Table: Average CAT-ASVAB and Limits

	Limits on TV	Limits on Curfew	Limits on Friends
Jointly/Child	49059	52659	51592
Parents	47115	44831	32687
T-test	0.4	0	0

all cohorts, pooled data

Introduction

Statistics on Limits

Table: Limits and Race

	Age 12-13				Age 13-14				Age 14-15			
	Parents	Child	Jointly	N	Parents	Child	Jointly	N	Parents	Child	Jointly	N
	Curfew											
Hispanic	67.45	3.94	28.61	381	60.06	5.38	34.56	353	52.19	5.83	41.98	343
Black	75.52	3	21.48	433	63.06	7.65	29.29	379	56.87	5.49	37.64	364
White	64.55	2.37	33.08	928	51.76	4.42	43.38	883	39.51	9.5	50.98	863
	Friends' Limits											
Hispanic	28.16	43.36	28.16	380	13.31	55.81	30.88	353	10.17	62.5	27.33	344
Black	34.87	36.49	28.64	433	17.32	52.23	30.45	381	14.25	56.99	28.77	365
White	17.35	51.08	31.57	928	10.24	62.8	26.96	879	7.86	68.21	23.93	865
	TV Limits											
Hispanic	35.96	35.17	28.87	381	18.64	48.59	32.77	354	14.53	55.81	29.65	344
Black	35.33	35.33	29.33	433	20.63	52.65	26.72	378	10.68	62.74	26.58	365
White	37.5	27.8	34.7	928	20.39	50.4	29.22	883	15.95	60.12	23.93	865

The game

Information structure and order of moves

- There are two forward looking players: the parent and the child

The game

Information structure and order of moves

- There are two forward looking players: the parent and the child
- Complete information, finite horizon (T periods)

The game

Information structure and order of moves

- There are two forward looking players: the parent and the child
- Complete information, finite horizon (T periods)
- The conflict b/w players stems from a mismatch in preferences, i.e. there are no behavioral differences which can be advocated to justify parental intervention

The order of moves on the stage game is as follows:

- Conditional on the stock of human capital, K_t and the beliefs about parents choose a parenting style $\rho_t \in \mathbb{R}^n$

The game

Information structure and order of moves

- There are two forward looking players: the parent and the child
- Complete information, finite horizon (T periods)
- The conflict b/w players stems from a mismatch in preferences, i.e. there are no behavioral differences which can be advocated to justify parental intervention

The order of moves on the stage game is as follows:

- Conditional on the stock of human capital, K_t and the beliefs about parents choose a parenting style $\rho_t \in \mathbb{R}^n$
- The child chooses an effort level $a_t \in [0, 1]$

The game

Information structure and order of moves

- There are two forward looking players: the parent and the child
- Complete information, finite horizon (T periods)
- The conflict b/w players stems from a mismatch in preferences, i.e. there are no behavioral differences which can be advocated to justify parental intervention

The order of moves on the stage game is as follows:

- Conditional on the stock of human capital, K_t and the beliefs about parents choose a parenting style $\rho_t \in \mathbb{R}^n$
- The child chooses an effort level $a_t \in [0, 1]$
- Child's new human capital K_{t+1} , becomes public

The game

Information structure and order of moves

- There are two forward looking players: the parent and the child
- Complete information, finite horizon (T periods)
- The conflict b/w players stems from a mismatch in preferences, i.e. there are no behavioral differences which can be advocated to justify parental intervention

The order of moves on the stage game is as follows:

- Conditional on the stock of human capital, K_t and the beliefs about parents choose a parenting style $\rho_t \in \mathbb{R}^n$
- The child chooses an effort level $a_t \in [0, 1]$
- Child's new human capital K_{t+1} , becomes public
- The stage game is repeated

Primitives

Preferences

- Child cares about leisure and his adult human capital

$$u_t = \begin{cases} u(l_t) & \text{if } t = 1, 2, \dots, T \\ \Xi(K_{T+1}) & \text{when the game is over} \end{cases}$$

with u and Ξ increasing

- Parent cares suffers from the monitoring cost and cares about the child's adult human capital

$$w_t = \begin{cases} -c(\rho_t) & \text{if } t = 1, 2, \dots, T \\ \Pi(K_{T+1}) & \text{when the game is over} \end{cases}$$

with c and Π increasing

Primitives

The Evolution of Skills

- Cognitive skills evolve stochastically according to a distribution $F(K_{t+1}|a_t, K_t)$ such that
 - $K_{t+1} \in [\underline{k}, \bar{k}]$ for any K_t and a_t
 - $F(K_{t+1}|a'', K_t)$ FOSD $F(K_{t+1}|a', K_t)$ for any $a'' > a'$, K_t
 - $F(K_{t+1}|a_t, K'')$ FOSD $F(K_{t+1}|a_t, K')$ for any $K'' > K'$, a_t
- I capture evolution in noncognitive skills through the changes in the discount factor $\delta(K_t)$. Endogenous formation of time preferences. A possible parametrization is:

$$\delta(K_t) = \frac{\exp(K_t)}{1 + \exp(K_t)}$$

- The model captures:
 - The cross and self-productivity of skills:
 $\uparrow \delta(K_t) \Rightarrow \uparrow a_t \Rightarrow \uparrow K_{t+1} \Rightarrow \delta(K_{t+1})$

The Child's Constraint

- The child solves his maximization problem under the constraint $a \geq \tau$

The Child's Constraint

- The child solves his maximization problem under the constraint $a \geq \tau$
- $\tau \in [0, 1]$ is a random variable with conditional distribution $G(\tau|\rho)$

The Child's Constraint

- The child solves his maximization problem under the constraint $a \geq \tau$
- $\tau \in [0, 1]$ is a random variable with conditional distribution $G(\tau|\rho)$
- Let $R = (\rho_1, \dots, \rho_N)$ be ordered according to FOSD order, i.e.

$$\rho'' > \rho' \Leftrightarrow G(\tau|\rho'') \geq G(\tau|\rho')$$

e.g. ρ'' is stricter than ρ' if and only if $\rho'' > \rho'$

- A parenting style can be interpreted as a set of rules the parent imposes on the child's recreational activities

The Child's Constraint

- The child solves his maximization problem under the constraint $a \geq \tau$
- $\tau \in [0, 1]$ is a random variable with conditional distribution $G(\tau|\rho)$
- Let $R = (\rho_1, \dots, \rho_N)$ be ordered according to FOSD order, i.e.

$$\rho'' > \rho' \Leftrightarrow G(\tau|\rho'') \geq G(\tau|\rho')$$

e.g. ρ'' is stricter than ρ' if and only if $\rho'' > \rho'$

- A parenting style can be interpreted as a set of rules the parent imposes on the child's recreational activities
- The stochastic nature of the map between ρ and τ reflects the existence of an imperfect monitoring problem
- Higher the variance of τ conditional on ρ more pervasive the moral hazard problem

Strategies and Equilibria

- The parent's history is $H^{t,p} = (K^t, a^{t-1}, \rho^{t-1}, \tau^t)$
- The child's history is $H^{t,c} = (K^t, a^{t-1}, \rho^t, \tau^t)$ where $x^t = (x_1, \dots, x_t)$
- The parent's strategy is a map $\phi^p : H^{t,p} \rightarrow R$
- The child's strategy is a map $\phi^c : H^{t,c} \rightarrow [0, 1]$
- An optimal strategy profile for the child, $\vec{\phi}^c = \langle \phi_t^c(H^t) \rangle_{t=1}^T$, is given by a sequence of strategies such that:

$$\vec{\phi}^c \in \operatorname{argmax} E \left[\sum_{t=1}^T v(\phi_t^c(H^{t,c})) | \vec{\phi}^p \right] \quad (1)$$

- An optimal strategy profile for the parent, $\vec{\phi}^p = \langle \phi_t^p(H^{t,p}) \rangle_{t=1}^T$, is given by a sequence of strategies such that:

$$\vec{\phi}^p \in \operatorname{argmax} E \left[\sum_{t=1}^T w(\phi_t^p(H^{t,p})) | \vec{\phi}^c \right] \quad (2)$$

Recursive Representation

- I focus on Markov Strategies in which $H^{t,c} = (K_t, \tau_t)$, $H^{t,p} = K_t$
- The problem solved by the child is

$$V(K) = \left\langle \max_{a \geq \tau} \left[u(1-a) + \delta(K) \int_{\underline{k}}^{\bar{k}} V'(K') dF(K'|K, a) \right] \right\rangle$$

- $V' = \Xi$ if $t = T$
- V' incorporates the parent's strategy at $t+1$ if $t \leq T-1$

Recursive Representation

- I focus on Markov Strategies in which $H^{t,c} = (K_t, \tau_t)$, $H^{t,p} = K_t$
- The problem solved by the child is

$$V(K) = \left\langle \max_{a \geq \tau} \left[u(1-a) + \delta(K) \int_{\underline{k}}^{\bar{k}} V'(K') dF(K'|K, a) \right] \right\rangle$$

- $V' = \Xi$ if $t = T$
- V' incorporates the parent's strategy at $t+1$ if $t \leq T-1$
- Let $a(\tau, K)$ denote the child's best response function

Recursive Representation

- I focus on Markov Strategies in which $H^{t,c} = (K_t, \tau_t)$, $H^{t,p} = K_t$
- The problem solved by the child is

$$V(K) = \left\langle \max_{a \geq \tau} \left[u(1-a) + \delta(K) \int_{\underline{k}}^{\bar{k}} V'(K') dF(K'|K, a) \right] \right\rangle$$

- $V' = \Xi$ if $t = T$
- V' incorporates the parent's strategy at $t+1$ if $t \leq T-1$
- Let $a(\tau, K)$ denote the child's best response function
- The parent takes it as given and solves

$$W(k) = \left\langle \max_{\rho} \left[-c(\rho) + \beta \int_0^1 \int_k W'(K') dF(K'|K, a(\tau, K)) dG(\tau|\rho) \right] \right\rangle$$

- Let $\rho(K)$ denote the best response correspondence of the parent

Monotone Comparative Statics

- Let $f : X \times \Theta \rightarrow \mathbb{R}$ with $X \subseteq \mathbb{R}^n$, and $\Theta \subseteq \mathbb{R}^m$.
- We say that f has the single crossing property in (x, θ) , if and only if for any $x'' > x'$, $\theta'' > \theta'$

$$f(x'', \theta'') - f(x', \theta'') \geq (>)0 \Rightarrow f(x'', \theta') - f(x', \theta') \geq (>)0$$

Equivalently we say that $f(x, \theta'')$ dominates $f(x, \theta')$ according to the single crossing order $f(x, \theta'') \succeq_I f(x, \theta')$

Monotone Comparative Statics

- Let $f : X \times \Theta \rightarrow \mathbb{R}$ with $X \subseteq \mathbb{R}^n$, and $\Theta \subseteq \mathbb{R}^m$.
 - We say that f has the single crossing property in (x, θ) , if and only if for any $x'' > x'$, $\theta'' > \theta'$

$$f(x'', \theta'') - f(x', \theta'') \geq (>)0 \Rightarrow f(x'', \theta') - f(x', \theta') \geq (>)0$$

Equivalently we say that $f(x, \theta'')$ dominates $f(x, \theta')$ according to the single crossing order $f(x, \theta'') \succeq_I f(x, \theta')$

- We say that f has increasing differences in (x, θ) if and only if $\Delta(\theta) = f(x'', \theta) - f(x', \theta)$ is increasing in θ

Monotone Comparative Statics

- Let $f : X \times \Theta \rightarrow \mathbb{R}$ with $X \subseteq \mathbb{R}^n$, and $\Theta \subseteq \mathbb{R}^m$.
 - We say that f has the single crossing property in (x, θ) , if and only if for any $x'' > x'$, $\theta'' > \theta'$

$$f(x'', \theta'') - f(x', \theta'') \geq (>)0 \Rightarrow f(x'', \theta') - f(x', \theta') \geq (>)0$$

Equivalently we say that $f(x, \theta'')$ dominates $f(x, \theta')$ according to the single crossing order $f(x, \theta'') \succeq_I f(x, \theta')$

- We say that f has increasing differences in (x, θ) if and only if $\Delta(\theta) = f(x'', \theta) - f(x', \theta)$ is increasing in θ
- If f has ID in (x, θ) then f has the SCP in (x, θ)

Monotone Comparative Statics

- Let $f : X \times \Theta \rightarrow \mathbb{R}$ with $X \subseteq \mathbb{R}^n$, and $\Theta \subseteq \mathbb{R}^m$.
 - We say that f has the single crossing property in (x, θ) , if and only if for any $x'' > x'$, $\theta'' > \theta'$

$$f(x'', \theta'') - f(x', \theta'') \geq (>)0 \Rightarrow f(x'', \theta') - f(x', \theta') \geq (>)0$$

Equivalently we say that $f(x, \theta'')$ dominates $f(x, \theta')$ according to the single crossing order $f(x, \theta'') \succeq_I f(x, \theta')$

- We say that f has increasing differences in (x, θ) if and only if $\Delta(\theta) = f(x'', \theta) - f(x', \theta)$ is increasing in θ
- If f has ID in (x, θ) then f has the SCP in (x, θ)
- (Milgrom & Shannon): $\operatorname{argmax}_x f(x, \theta)$ is increasing in θ if and only if f has the SCP

Characterizing Equilibria: Punishing Strategy Equilibria

- Under which conditions is $\rho(K)$ decreasing in K for any t ?

Characterizing Equilibria: Punishing Strategy Equilibria

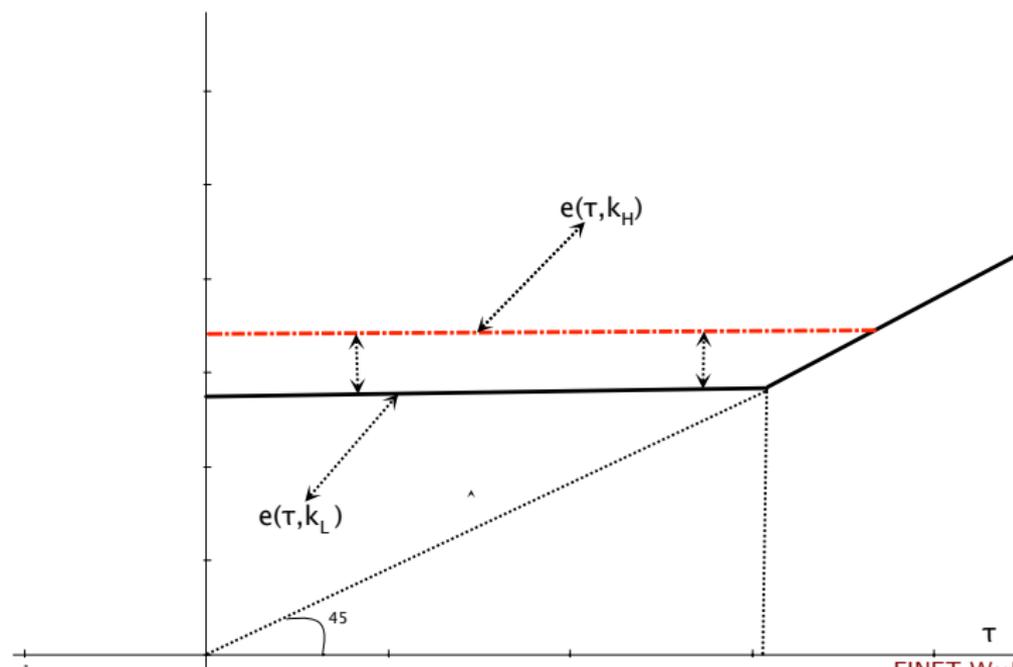
- Under which conditions is $\rho(K)$ decreasing in K for any t ?
- In order to apply the standard Milgrom-Shannon theorem I need to show that the objective function of the child has the single-crossing property in (K, ρ)

Characterizing Equilibria: Punishing Strategy Equilibria

- Under which conditions is $\rho(K)$ decreasing in K for any t ?
- In order to apply the standard Milgrom-Shannon theorem I need to show that the objective function of the child has the single-crossing property in (K, ρ)
- This is complicated by the fact that the parent's payoff function involve non-primitive objects - $a(\tau, K)$ and the value functions

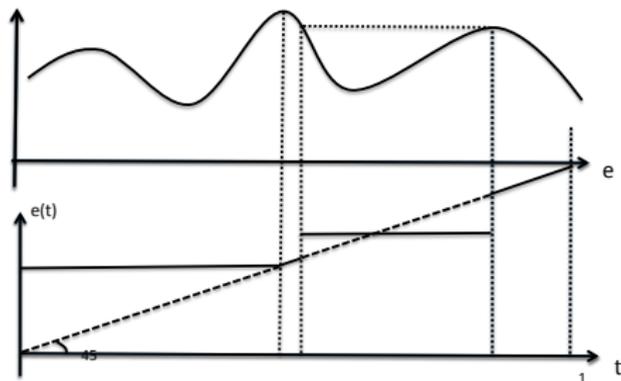
Best Responses: Graphical Analysis

Figure: Properties of Best Responses



Best Responses: Graphical Analysis

Figure: Properties of Best Responses



Properties of the Best Response Function

Lemma

- If $a(\tau, K)$ is increasing in K (I), then $a(\tau, K') \succeq_{IDO} a(\tau, K'')$ for any $K'' > K'$.
- If the objective function of the child is single-peaked (U) and (I) holds, $\Delta(K) = a(\tau'', K) - a(\tau', K)$ is decreasing in K

An intuitive approach:

- 1 If for any t (U) and (I) hold

Properties of the Best Response Function

Lemma

- If $a(\tau, K)$ is increasing in K (I), then $a(\tau, K') \succeq_{IDO} a(\tau, K'')$ for any $K'' > K'$.
- If the objective function of the child is single-peaked (U) and (I) holds, $\Delta(K) = a(\tau'', K) - a(\tau', K)$ is decreasing in K

An intuitive approach:

- 1 If for any t (U) and (I) hold
- 2 The parent's payoff function preserves the DD property of $\rho_t(K_t)$ then MS is applicable $\Rightarrow \rho_t(K_t)$ is decreasing in K_t for any t

Sufficient Conditions

Lemma

If

- 1) If $F(K|k, a) = F_1(K|k) + F_2(K|a)$
- 2) F_2 has the CDFC property, i.e. is convex in a
- 3) u is concave

then $\rho_t(K_t)$ is decreasing in K_t .

Main ingredients

- 1) exploits the fact that the sum of supermodular functions is supermodular by approximating an increasing function as a sum of steps function
- An increasing and concave (convex) transformation of a function with DD(ID) has the DD(ID) ((2) and (3))
- A theorem by Vives&Van Zandt preserves the DD property under integration

Data and Sample

The NLSY97 contains information on:

- the person setting the limit on the 3 activities (first three survey rounds for children born in 1983-1984)
- time spent watching TV and doing homework (first survey round for all cohorts)
- GPA achieved at the end of each academic (only for high school) year and PIAT test scores (first rounds all cohorts and all other rounds only 1984 cohorts)

Patterns

Homework

Table: Proportion of Children Spending Some Time Doing Homework in a Typical Week

Age	Black Children	Hispanic Children	White Children
12	88.51 (296)	85.42 (240)	92.81 (612)
13	86.47 (414)	85.17 (344)	91.5 (871)
14	82.25 (462)	83.14 (344)	90.22 (941)
15	82.71 (133)	82.68 (127)	83.71 (264)

Number of observations in parenthesis

Table: Time Spent Doing Homework in a Typical Week

Age	Black Children				Hispanic Children				White Children			
	Mean	Median	S.D	N	Mean	Median	S.D	N	Mean	Median	S.D	N
12-16	4.34	3.75	3.71	1309	4.75	4	3.8	1058	4.66	4	3.6	2694
12	4.53	4	3.23	262	5.81	5.5	3.59	205	5.12	4.5	3.3	568
13	5.10	4.5	3.53	358	5.55	5	3.57	293	4.98	4.16	3.62	797
14	5.29	4.5	2.29	380	5.48	5	3.33	286	5.27	5	3.42	849
15	5.79	5	3.65	110	5.92	5	3.51	105	5.38	4.5	3.54	221

Number of observations in parenthesis

Means and Medians are calculated on non-zero observations

Units: hours per week

Patterns

TV watching

Table: Time Spent Watching TV in a Typical Week

Age	Black Children				Hispanic Children				White Children			
	Mean	Median	S.D	N	Mean	Median	S.D	N	Mean	Median	S.D	N
12-15	24.49	22	14.84	1280	20.06	17	13.28	1058	16.37	14	11.25	2716
12	23.39	21	14.19	289	18.59	16	12.28	244	16.72	14	11.82	622
13	24.38	21	15.5	408	20.35	18	13.48	341	16.25	14	10.67	884
14	25.88	25	14.4	447	20.79	18	13.83	344	16.28	14	11.33	943
15	22.53	18	15.34	136	20.11	17	13.01	129	16.25	14	11.58	267

Number of observations in parenthesis

Means and Medians are calculated on non-zero observations

Units: hours per week

Multiplicity of equilibria

- Under (I) and (U) all the SPNE of the game have the (PS) property: there exists a matrix of cutoffs

$$\underbrace{c}_{(n-1) \times T} = (c_1, c_2, \dots, c_T)$$

such that

- $\rho_t(k_{t-1}) = \rho_i \Leftrightarrow c_{i-1} \leq k_{t-1} \leq c_i$

Multiplicity of equilibria

- Under (I) and (U) all the SPNE of the game have the (PS) property: there exists a matrix of cutoffs

$$\underbrace{\mathbf{c}}_{(n-1) \times T} = (c_1, c_2, \dots, c_T)$$

such that

- $\rho_t(k_{t-1}) = \rho_i \Leftrightarrow c_{i-1} \leq k_{t-1} \leq c_i$
- Given a set of cutoffs \mathbf{c} , $a(K, \tau)$ is unique

Multiplicity of equilibria

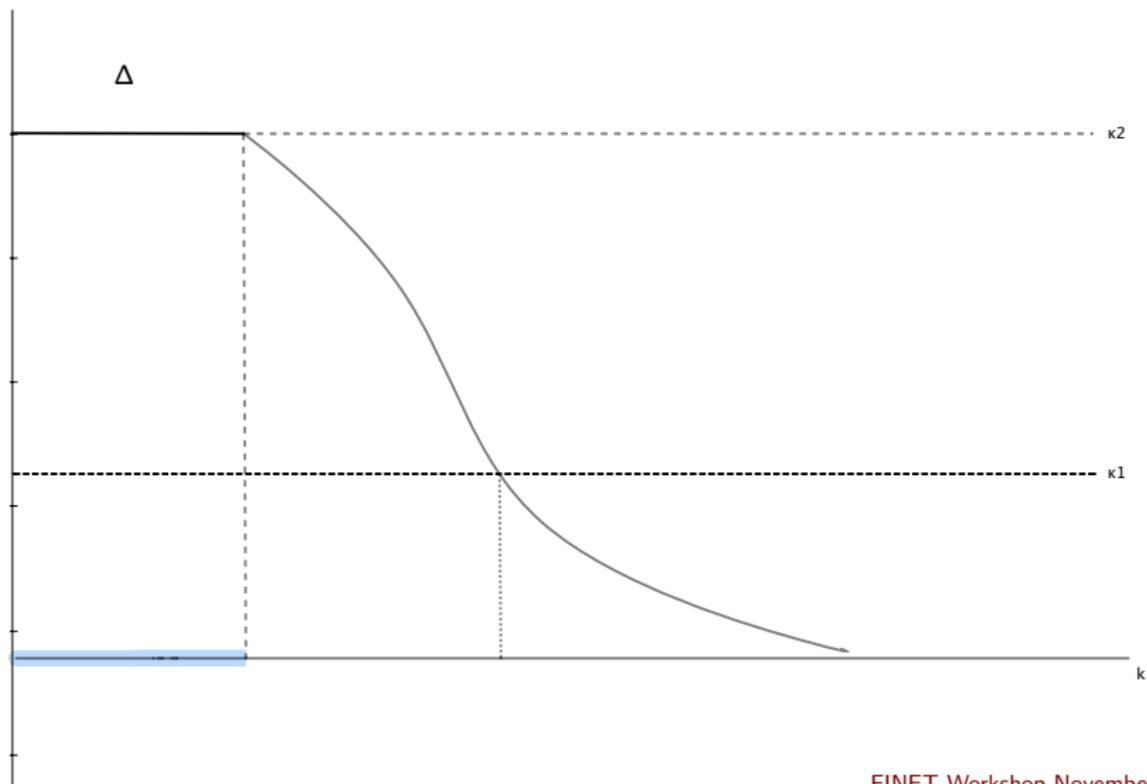
- Under (I) and (U) all the SPNE of the game have the (PS) property: there exists a matrix of cutoffs

$$\underbrace{\mathbf{c}}_{(n-1) \times T} = (c_1, c_2, \dots, c_T)$$

such that

- $\rho_t(k_{t-1}) = \rho_i \Leftrightarrow c_{i-1} \leq k_{t-1} \leq c_i$
- Given a set of cutoffs \mathbf{c} , $a(K, \tau)$ is unique
- Given $a(K, \tau)$ the matrix \mathbf{c} is not unique due to possible corner solutions and because of the dynamic aspect of the problem solved by the child

Figure: Multiple Equilibria



Two Step Estimation

- It is well known that multiple equilibria pose problem for the identification of the structural parameters due to the incompleteness problem

Two Step Estimation

- It is well known that multiple equilibria pose problem for the identification of the structural parameters due to the incompleteness problem
- There is no “general” method to deal with multiple equilibria

Two Step Estimation

- It is well known that multiple equilibria pose problem for the identification of the structural parameters due to the incompleteness problem
- There is no “general” method to deal with multiple equilibria
- I adopt a 2-step estimator analogous to the one proposed by Moro (IER 2003) which avoids equilibrium selection

Two Step Estimation

- It is well known that multiple equilibria pose problem for the identification of the structural parameters due to the incompleteness problem
- There is no “general” method to deal with multiple equilibria
- I adopt a 2-step estimator analogous to the one proposed by Moro (IER 2003) which avoids equilibrium selection
 - First step: solve the child's problem numerically and estimate F , G , δ , u together with \mathbf{c} (child's response is a function) through SML using measurement error
 - Second step: given \mathbf{c} recover w_t using a GMM estimator based on the equilibrium conditions

First Step

Measures and Choices

The NLSY97 contains

- 2 measures of children's cognitive skills: GPA and PIAT math test scores
 - I use a linear factor model assuming that they are proxies for the state variable of the model

$$GPA_t = n_0 + n_1 k_t + \epsilon_t^G$$
$$PIAT_t = m_0 + m_1 k_t + \epsilon_t^P$$

with ϵ_t^G and ϵ_t^P being normally distributed

First Step

Measures and Choices

The NLSY97 contains

- 2 measures of children's cognitive skills: GPA and PIAT math test scores
 - I use a linear factor model assuming that they are proxies for the state variable of the model

$$\begin{aligned}GPA_t &= n_0 + n_1 k_t + \epsilon_t^G \\PIAT_t &= m_0 + m_1 k_t + \epsilon_t^P\end{aligned}$$

with ϵ_t^G and ϵ_t^P being normally distributed

- 2 measures of time allocation : time spent watching TV and doing homework which are part of the choice set of the child
 - I adopt an hurdle model for the measurement equation to deal with both the intensive and the extensive margin:

$$g(e^o) = \begin{cases} \rho e & \text{if } e^o = 0 \\ \frac{1-\rho e}{1-G(0|e)} g(e^o|e) & \text{if } e^o > 0 \end{cases}$$

where

- e^o denotes the observed effort (time spent doing homework), while e the optimal effort implied by the model
- G is the CDF of a normal $g(\cdot|e)$ with mean $\lambda_{0,e} + \lambda_{1,e}e$ and variance σ_e^2

First Step

Measures and Choices

The NLSY97 contains

- 2 measures of children's cognitive skills: GPA and PIAT math test scores
 - I use a linear factor model assuming that they are proxies for the state variable of the model

$$GPA_t = n_0 + n_1 k_t + \epsilon_t^G$$
$$PIAT_t = m_0 + m_1 k_t + \epsilon_t^P$$

with ϵ_t^G and ϵ_t^P being normally distributed

First Step

Measures and Choices

The NLSY97 contains

- 2 measures of children's cognitive skills: GPA and PIAT math test scores
 - I use a linear factor model assuming that they are proxies for the state variable of the model

$$\begin{aligned}GPA_t &= n_0 + n_1 k_t + \epsilon_t^G \\PIAT_t &= m_0 + m_1 k_t + \epsilon_t^P\end{aligned}$$

with ϵ_t^G and ϵ_t^P being normally distributed

- 2 measures of time allocation : time spent watching TV and doing homework which are part of the choice set of the child
 - I adopt an hurdle model for the measurement equation to deal with both the intensive and the extensive margin:

$$g(e^o) = \begin{cases} \sigma_e & \text{if } e^o = 0 \\ \frac{1 - \sigma_e}{1 - G(0|e)} g(e^o|e) & \text{if } e^o > 0 \end{cases}$$

where

- e^o denotes the observed effort (time spent doing homework), while e the optimal effort implied by the model
- G is the CDF of a normal $g(\cdot|e)$ with mean $\lambda_{0,e} + \lambda_{1,e}e$ and variance σ_e^2
- An analogous model is adopted to model TV viewership
- I use the responses on the limits to construct three binary indicators (1 if the the parent decides alone, 0 otherwise). Each response is allowed to be misclassified with positive probability

$$\Pr(\rho^o(j) = 1 | \rho(j) = 1) = E_j + (1 - E_j) \Pr(\rho(j) = 1)$$

First Step

Sample and Data-Model Map

To map the model to the data I

- I model parent-child interaction from grade 6 to grade 12

First Step

Sample and Data-Model Map

To map the model to the data I

- I model parent-child interaction from grade 6 to grade 12
- To map the model to the data I divide the academic year into two semesters: fall and winter, which gives 14 “periods”

First Step

Sample and Data-Model Map

To map the model to the data I

- I model parent-child interaction from grade 6 to grade 12
- To map the model to the data I divide the academic year into two semesters: fall and winter, which gives 14 “periods”

In the sample I include

- Children who have no siblings living in the household at the time of the interview (treat in and out moves as exogenous)

First Step

Sample and Data-Model Map

To map the model to the data I

- I model parent-child interaction from grade 6 to grade 12
- To map the model to the data I divide the academic year into two semesters: fall and winter, which gives 14 “periods”

In the sample I include

- Children who have no siblings living in the household at the time of the interview (treat in and out moves as exogenous)
- High school graduates (do not model dropping out decisions) with a normal grade progression

First Step

Estimation Algorithm

Several issues if one wants to estimate the model by SML:

- the model contains an unobservable state variable (τ)

First Step

Estimation Algorithm

Several issues if one wants to estimate the model by SML:

- the model contains an unobservable state variable (τ)
- k_{t-1} is observable up to measurement error

First Step

Estimation Algorithm

Several issues if one wants to estimate the model by SML:

- the model contains an unobservable state variable (τ)
- k_{t-1} is observable up to measurement error
- there are missing variables for my measures of human capital
- computing conditional probabilities requires to integrate out all the possible realizations of the state variables

First Step

Estimation Algorithm

Several issues if one wants to estimate the model by SML:

- the model contains an unobservable state variable (τ)
- k_{t-1} is observable up to measurement error
- there are missing variables for my measures of human capital
- computing conditional probabilities requires to integrate out all the possible realizations of the state variables
- to overcome the computational burden I implement the method developed by Keane and Wolpin (IER 2001) which
 - only requires to simulate “outcome” histories, i.e. only needs unconditional simulations
 - uses the densities of the measurement/classification errors to reconcile the predictions of the model with the observations in the data

First Step

Data Limitations, Heterogeneity and Identification

- Because “effort” is observed only once, permanent unobserved heterogeneity in “mental abilities” cannot be identified using the information on the child’s skills (GPA and PIAT)

First Step

Data Limitations, Heterogeneity and Identification

- Because “effort” is observed only once, permanent unobserved heterogeneity in “mental abilities” cannot be identified using the information on the child’s skills (GPA and PIAT)
- As in Cunha-Heckman (2008) I assume that all the heterogeneity in abilities is captured by my measures (i.e. no “fixed effect”)

First Step

Data Limitations, Heterogeneity and Identification

- Because “effort” is observed only once, permanent unobserved heterogeneity in “mental abilities” cannot be identified using the information on the child’s skills (GPA and PIAT)
- As in Cunha-Heckman (2008) I assume that all the heterogeneity in abilities is captured by my measures (i.e. no “fixed effect”)
- Parents are allowed to differ in their monitoring cost. There are two parental types (strict and permissive)

First Step

Data Limitations, Heterogeneity and Identification

- Because “effort” is observed only once, permanent unobserved heterogeneity in “mental abilities” cannot be identified using the information on the child’s skills (GPA and PIAT)
- As in Cunha-Heckman (2008) I assume that all the heterogeneity in abilities is captured by my measures (i.e. no “fixed effect”)
- Parents are allowed to differ in their monitoring cost. There are two parental types (strict and permissive)
- The only source of heterogeneity across children is k_0

Key identification arguments

Conditional on a matrix \mathbf{c} :

- the observed variation in effort as a function of k is informative about the parameters entering $\delta(k)$

First Step

Data Limitations, Heterogeneity and Identification

- Because “effort” is observed only once, permanent unobserved heterogeneity in “mental abilities” cannot be identified using the information on the child’s skills (GPA and PIAT)
- As in Cunha-Heckman (2008) I assume that all the heterogeneity in abilities is captured by my measures (i.e. no “fixed effect”)
- Parents are allowed to differ in their monitoring cost. There are two parental types (strict and permissive)
- The only source of heterogeneity across children is k_0

Key identification arguments

Conditional on a matrix \mathbf{c} :

- the observed variation in effort as a function of k is informative about the parameters entering $\delta(k)$
- the parameters entering the payoff functions are identified by unconditional observed variations of time allocation choices

First Step

Data Limitations, Heterogeneity and Identification

- Because “effort” is observed only once, permanent unobserved heterogeneity in “mental abilities” cannot be identified using the information on the child’s skills (GPA and PIAT)
- As in Cunha-Heckman (2008) I assume that all the heterogeneity in abilities is captured by my measures (i.e. no “fixed effect”)
- Parents are allowed to differ in their monitoring cost. There are two parental types (strict and permissive)
- The only source of heterogeneity across children is k_0

Key identification arguments

Conditional on a matrix \mathbf{c} :

- the observed variation in effort as a function of k is informative about the parameters entering $\delta(k)$
- the parameters entering the payoff functions are identified by unconditional observed variations of time allocation choices
- Given a stock of human capital, the variations in the effort conditional on an observed parenting style pins down the parameters entering $G(\tau|\rho)$
- The matrixes \mathbf{c} are identified by the observed variations in the parenting style choices conditional on the human capital of the child (analogous to an ordered logit with heterogeneous cutoffs)

Second Step

- The goal of the second step is to recover the parameters into Π and the costs κ_i
 - The estimated matrix $\hat{\mathbf{c}}$ provides, for each parental type at most $T \times (n - 1)$ moments where

$$\int W(K) dF(K|a(\hat{\mathbf{c}}_i, \rho(\hat{\mathbf{c}}_i)), \hat{\mathbf{c}}_i) = \kappa_{i-1} - \kappa_i > 0$$

where in the last period $W = \Pi$. Let $\#\Pi$ denote the number of parameters entering into Π

Second Step

- The goal of the second step is to recover the parameters into Π and the costs κ_i
 - The estimated matrix $\hat{\mathbf{c}}$ provides, for each parental type at most $T \times (n - 1)$ moments where

$$\int W(K) dF(K|a(\hat{\mathbf{c}}_i, \rho(\hat{\mathbf{c}}_i)), \hat{\mathbf{c}}_i) = \kappa_{i-1} - \kappa_i > 0$$

where in the last period $W = \Pi$. Let $\#\Pi$ denote the number of parameters entering into Π

- Exact point-identification is achieved if and only if $\#\Pi = T = 14$
- Overidentification is the typical case

Second Step

- The goal of the second step is to recover the parameters into Π and the costs κ_i
 - The estimated matrix $\hat{\mathbf{c}}$ provides, for each parental type at most $T \times (n - 1)$ moments where

$$\int W(K) dF(K|a(\hat{\mathbf{c}}_i, \rho(\hat{\mathbf{c}}_i)), \hat{\mathbf{c}}_i) = \kappa_{i-1} - \kappa_i > 0$$

where in the last period $W = \Pi$. Let $\#\Pi$ denote the number of parameters entering into Π

- Exact point-identification is achieved if and only if $\#\Pi = T = 14$
- Overidentification is the typical case

First Step

Parametrizations

Preferences

$$v(\alpha_t) = \begin{cases} (1 - e_t)^\eta & \text{if } t < T + 1 \\ \Xi(k_T) & \text{if } t = T + 1 \text{ (the game is over)} \end{cases}$$

with $\eta \in (0, 1)$

$$\Xi(k_T) = \frac{1}{\xi} \left\{ 1 - \exp \left[-\xi \left(\frac{k_T^{1-\sigma} - 1}{1-\sigma} \right) \right] \right\}$$

with $\sigma > 0$ and $\xi > 0$

$$\delta(k) = \frac{\vartheta_0}{\vartheta_0 + \exp(-\vartheta_1 k)}$$

with $\vartheta_0 > 0$

First Step

Parametrizations

Technologies

- $G(\tau|\lambda) = \text{Beta}[d(\rho_t), 1]$ with $\tau \in [0, 1], \lambda_1 > 0$
- I parametrize $d(\rho_t)$ as follows

$$d(\rho_t) = \frac{\lambda_0 \rho_t}{1 + \lambda_0 \rho_t}$$

there exists a positive probability of misclassification

- The human capital production is the sum of two power density production functions

$$F(K|e, k) = \frac{K^{a(e)}}{2} + \frac{K^{b(k)}}{2} \quad \text{with } K \in [0, 1]$$

with

$$a(e) = \frac{\theta_0 + e^{\theta_1}}{1 + \theta_0 + e^{\theta_1}}$$
$$b(k) = \frac{\exp(\theta_2 k)}{1 + \exp(\theta_2 k)}$$

with $\theta_0 > 0$, $\theta_1 \in (0, 1)$ and $\theta_2 > 0$.

Estimates

Table: Estimates

parameter	Estimate	S.E.
η	0.24	0.003
σ	0.14	0.002
ξ	24.52	8.64
ϑ_0	0.48	0.009
ϑ_1	0.57	0.04
λ_0^{TV}	0.23	0.008
λ_0^{curfew}	0.68	0.004
$\lambda_0^{friends}$	0.02	0.001
θ_0	7.82	1.14
θ_1	8.12	2.34
θ_2	1.45	0.07

Model Fit

Homework Doing

Table: % of Children Studying

age	Data	Model
12	91.24	92.48
13	89.37	92.14
14	87.65	88.42
15	87.14	89.24

Table: Average Study Time

age	Data	Model
12	4.55	4.82
13	4.53	4.72
14	4.45	4.62
15	4.57	4.81

Model Fit

Limits

Table: Proportion of Parents Setting the Curfew

age	Data	Model
12	68.74	71.12
13	66.59	70
14	60.77	64.72
15	53.22	58.83
16	48.27	52.72

Model Fit

Limits

Table: Proportion of Parents Setting Limits on TV shows

age	Data	Model
12	39.21	42.65
13	32.03	34.71
14	21.62	24.98
15	13.91	15.32
16	11.16	13.21

A Policy Question

- Governments intervention in disciplining children is subject to debate :
In the early days of the Labour government there was much discussion in the media about where the boundary lay between interferences and appropriate involvement. There are some who view the family as a private institutions and believe that, except in the extreme cases, it should be largely free from state interferences. On the other hand there are those who take the position that government does have a role in enhancing support for the family - Coleman and Roker
- Provided that the enforcement cost is low, why not eliminating parental monitoring cost?

A Policy Question

- Governments intervention in disciplining children is subject to debate:
In the early days of the Labour government there was much discussion in the media about where the boundary lay between interferences and appropriate involvement. There are some who view the family as a private institutions and believe that, except in the extreme cases, it should be largely free from state interferences. On the other hand there are those who take the position that government does have a role in enhancing support for the family - Coleman and Roker
- Provided that the enforcement cost is low, why not eliminating parental monitoring cost?

Counterfactuals

Tiger Mother

- No matter what: you stay home, no TV, no friends
- The ATE of such a policy on PIAT test scores would be small: an increase of about 3% in the PIAT test scores and of 10% in the GPA

Counterfactuals

Tiger Mother

- No matter what: you stay home, no TV, no friends
- The ATE of such a policy on PIAT test scores would be small: an increase of about 3% in the PIAT test scores and of 10% in the GPA
- However there are important distributional effects

Table: Distributional Effect on GPA

<i>P1</i>	<i>P2</i>	<i>P3</i>	<i>P4</i>	<i>P5</i>	<i>P6</i>	<i>P7</i>	<i>P8</i>	<i>P9</i>	<i>P10</i>
19%	17.6%	12.4%	8.7%	4.2%	2.9%	0.5%	-4.7%	-7.2%	-11.8%

Table: Distributional Effect on PIAT

<i>G1</i>	<i>G2</i>	<i>G3</i>	<i>G4</i>	<i>G5</i>	<i>G6</i>	<i>G7</i>	<i>G8</i>	<i>G9</i>	<i>G10</i>
10.1%	8.3%	5.1%	2.3%	1.9%	0.1%	-0.3%	-0.4%	-2.1%	-1.6%

Counterfactuals

Complete Freedom

- Reassigning property rights: parent as a concierge

Counterfactuals

Complete Freedom

- Reassigning property rights: parent as a concierge
- The ATE on PIAT and GPA is always negative: a decrease of about 7% in the PIAT test scores and of 15% in the GPA

Counterfactuals

Complete Freedom

- Reassigning property rights: parent as a concierge
- The ATE on PIAT and GPA is always negative: a decrease of about 7% in the PIAT test scores and of 15% in the GPA
- However the are important distributional effects

Table: Distributional Effect on GPA

<i>P1</i>	<i>P2</i>	<i>P3</i>	<i>P4</i>	<i>P5</i>	<i>P6</i>	<i>P7</i>	<i>P8</i>	<i>P9</i>	<i>P10</i>
-14.6%	-11.8%	-9.6%	-7.5%	-4.8%	-3.9%	-1.7%	-0.8%	-0.3%	-0.1%

Table: Distributional Effect on PIAT

<i>P1</i>	<i>P2</i>	<i>P3</i>	<i>P4</i>	<i>P5</i>	<i>P6</i>	<i>P7</i>	<i>P8</i>	<i>P9</i>	<i>P10</i>
-9.1%	-7.3%	-5.8%	-5.6%	-3.9%	-2.1%	-1.3%	-0.4%	0.1%	0.5%

- Welfare Analysis

Road Ahead

- Welfare Analysis
- Reshuffling: optimal assignment problem

Longer Term Research Agenda:

- Monetary Incentives

Road Ahead

- Welfare Analysis
- Reshuffling: optimal assignment problem

Longer Term Research Agenda:

- Monetary Incentives
- Multiple Siblings

Road Ahead

- Welfare Analysis
- Reshuffling: optimal assignment problem

Longer Term Research Agenda:

- Monetary Incentives
- Multiple Siblings
- Asymmetric Information